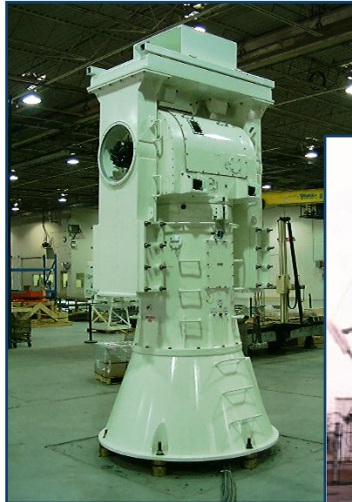


Model P4800 Post Pedestal

Model P4800 Pedestal Features

- Heavy Duty Tracking Pedestal
- Dual Gear Driven with Bias, to Eliminate Backlash
- Up to 30 deg/sec Velocity
- Servo Driven Twin Motors on Elevation and Azimuth
- Precision Resolvers or Position Encoders for Angular Feedback
- 4000 Pound Payload Weight
- Environmentally Sealed



Model P4800 Post Pedestal

Ideal for applications such as tracking radars, satellite tracking antennas, communications systems, ELINT antennas, and EW simulators, the Kratos Model P4800 Post Pedestal features dual, geared drives in azimuth and elevation. Drive systems are biased electronically to eliminate mechanical backlash in the gearing. The resulting system provides high reliability and accurate pointing for RF antennas. Pedestal and control electronics produce wide bandwidth servo performance with very low jitter suitable for automatic tracking. The pedestal will support balanced loads of up to 4000 pounds at velocities of 30 deg/sec. Optional features include slip rings, rotary joints, and custom load support structures.

Only tested, field-proven components are used in the design of this pedestal. Hardware is military-temperature rated, and mechanical design is rugged. Reliability and long life are the hallmarks of this pedestal.

Features

Dual Drives

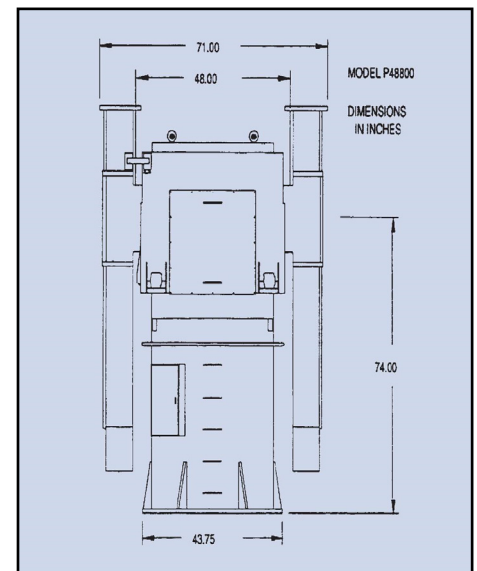
Each axis contains dual, opposed drives consisting of DC servo motors operating through reduction gears. Axes have failsafe friction brakes and manual drives. By electronically biasing the amplifiers, the drive motors keep the gear trains constantly in contact, eliminating geartrain backlash.

Position Encoders

The position encoder in each axis is a resolver transmitter driven by anti-backlash gearing. Optional optical encoders or rotary inductosyns may also be used.

Bearings

The bearings are large diameter bull gear bearing with overturning moment capacity of 85,000 ft-lbs. This ensures a very high safety margin; yet provides necessary stiffness to meet the specifications of highly accurate systems.



Seals

Teflon lip seals environmentally protect the rotating interfaces of the positioned, effectively designed to exclude water, dirt, and dust while producing minimum system friction.

Materials

The positioned is constructed of the highest quality materials, selected to provide maximum corrosion resistance with minimum weight. Typical components include 6061 aluminum alloy for structural material and cadmium plated 300 series CRES fasteners.

Axis Travel

Physical stops limit the rotation in each axis. The elevation axis travel is -10° to $+95^{\circ}$, while the azimuth axis travel is $+180^{\circ}$ plus over-travel. Continuous azimuth travel is available with optional slip rings.

Riser

Customer requirements determine riser height.

Stow Pins

Stow pins are mounted on each axis to lock the axes in position for storage or transportation.

Load Platform (Optional)

Custom-designed platforms are bolted to the load supports of the elevation axis.

Amplifiers

The pedestal can be controlled with a Model 3200 Servo Amplifier.

Performance				Configuration	
Velocity				Pedestal Type	Elevation-over-Azimuth post
Azimuth	0.05°/sec min.	20°/sec rated	30°/sec max.	Drive System	DC motor/planetary gear head (dual drive)
Elevation	0.05°/sec min.	20°/sec rated	30°/sec max.	Servo Amplifier	Pulse width modulated (PWM) amplifier with analog rate loop electronics
Acceleration				Pedestal Weight	10,000 pounds
Azimuth	40°/sec ²			Payload Weight	4,000 pounds (not including counterweights)
Elevation	40°/sec ²			Interfaces	
Accuracy				Mechanical	
Bearing Wobble	0.01°			Base	40.0 inch diameter bolt circle, 8 holes equally spaced, 1.00 inch diameter holes
Orthogonality	0.02°			Payload	Payload supports are optional, determined by customer specification.
Backlash	0.018° (0.00° dual drive)			Electrical	
Output Torque, rated velocity (dual drive)				Base	MS Type Connectors
Azimuth	20,000 ft/lbs.			Payload	MS Type Connectors
Elevation	8,000 ft/lbs.			Ground Stud	Located at base of pedestal
Rate Loop Bandwidth, at rated inertia (6700 ft/ibs-sec²)				Features	
Azimuth	13 Hz			Finish	Pretreatment; Final coat customer specified
Elevation	13 Hz			Handcranks	Electrically Interlocked
Compliance (dual drive)				Failsafe Brakes	Both Axes
Azimuth	1.5x10 ⁻⁸ RADft./lbs.			Safety Switch	Mounted at Pedestal Base
Elevation	1.5x10 ⁻⁸ RADft./lbs.			Slip Rings (optional)	Azimuth Axis with 6 inch through hole
Static Repeatability	+/- .010				

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